Viper 650/850

6-Axis robot family, ideal for complex mechanical assemblies, material handling, inspection, and packaging

- 5 kg payload, high-efficiency, low-inertia drives and a lightweight arm to deliver maximum acceleration
- High-resolution, absolute encoders to provide high accuracy, superior slow-speed following, and easy calibration
- Available in 653 mm and 855 reach options to accommodate a wide variety of applications
- Integrated Control with EtherCAT connectivity or Standard Control with Ethernet connectivity
- Ethernet/IP control via ePLC implementation
- Clean room and IP65 models available



Ordering Information

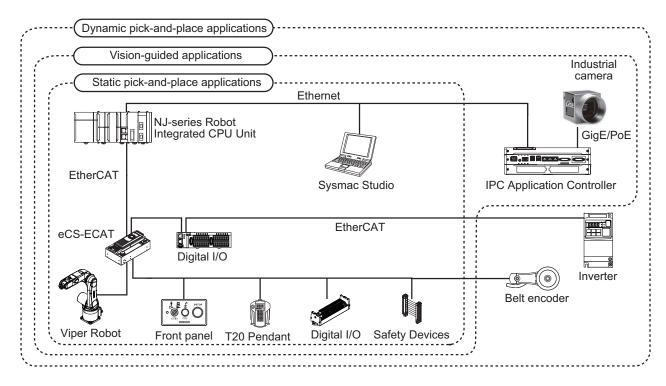
Product Model	Reach (mm)	Control Type	Connectible Controller	Protections	Part Number
				IP20	17210-36000
		Standard	eMB-60R	IP65	17210-36010
				Cleanroom	17210-36020
			eMB-60R, ePLC	IP20	17211-36000
				IP65	17211-36010
				Cleanroom	17211-36020
			eMB-60R, SmartController EX	IP20	17212-36000
				IP65	17212-36010
\/:CF0	653			Cleanroom	17212-36020
Viper 650				IP20	17213-36000
			eMB-60R, Add-On	IP65	17213-36010
				Cleanroom	17213-36020
				IP20	17214-36000
			eMB-60R, ePLC, SmartController EX	IP65	17214-36010
			Gillartoonii olici EX	Cleanroom	17214-36020
				IP20	RL6-2066000
		Integrated	eCS-eCAT	IP65	RL6-2066010
		-		Cleanroom	RL6-2066020
			eMB-60R	IP20	17210-38000
				IP65	17210-38010
				Cleanroom	17210-38020
	855	Standard	eMB-60R, ePLC	IP20	17211-38000
				IP65	17211-38010
				Cleanroom	17211-38020
			eMB-60R, SmartController EX	IP20	17212-38000
				IP65	17212-38010
\/:050				Cleanroom	17212-38020
Viper 850			eMB-60R, Add-On	IP20	17213-38000
				IP65	17213-38010
				Cleanroom	17213-38020
			eMB-60R, ePLC, SmartController EX	IP20	17214-38000
				IP65	17214-38010
				Cleanroom	17214-38020
		Integrated	eCS-eCAT	IP20	RL6-2068000
				IP65	RL6-2068010
				Cleanroom	RL6-2068020

Viper Series

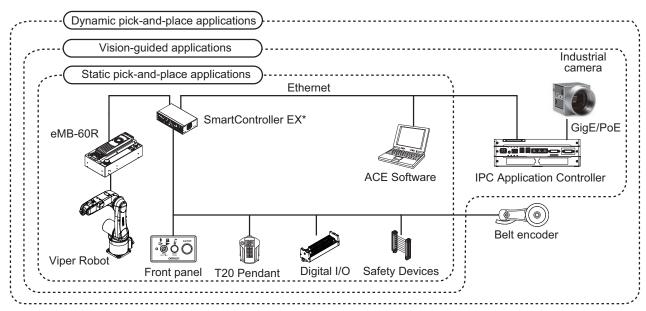
System Configuration

Typical system configurations are shown below. Other equipment and connections are possible.

Integrated Control



Standard Control



Without the optional SmartController EX, ethernet and accessories connect to the eMB-60R.

Specifications

	láo un	Model		
Item		650	850	
Number of axes		6		
Reach		653 mm	855 mm	
Maximum Payload*1		5 kg		
Repeatability	XY	±0.02 mm	±0.03 mm	
Joint Range	Joint 1	±170°		
	Joint 2	-190°, +45°		
	Joint 3	-29°, +256°		
	Joint 4	±190°		
	Joint 5	±120°		
	Joint 6	±360°		
	Joint 4	0.295 kg-m ²		
Inertia Moment (Max.)	Joint 5	0.295 kg-m ²		
	Joint 6	0.045 kg-m ²		
	Joint 1	328°/s	250°/s	
	Joint 2	300°/s	250°/s	
Joint Speeds	Joint 3	375°/s	250°/s	
oomit opecus	Joint 4	375°/s	375°/s	
	Joint 5	375°/s	375°/s	
	Joint 6	600°/s	600°/s	
Electrical Requirements		24 VDC: 6 A 200 to 240 VAC: 10 A, single-phase		
Protection	Base	IP40/IP54*2		
Protection	Robot Joints (J4, J5, J6)	IP40/IP65*3		
Cleanroom Class		Class 1	0*4	
Mounting		Table, inv		
Environmental	Ambient Temperature	5° to 40°C		
Requirements	Humidity Range	5% to 90% non-	condensing	
Weight		34 kg	36 kg	
	On-board I/O (Input/Output)	12/8		
	Conveyor tracking input	2		
	RS-232C serial	1		
	communications port	'		
Basic configuration	Programming	ACE / Sysmac Studio 64-bit, ePLC		
	environment*5	•		
	Robot Vision Manager	Yes		
	ePLC Connect*6	Yes		
	ePLC I/O*6	Yes		
	Standard Control	eMB-60R with optional SmartController EX*7		
Connectible Controller	Integrated Control	eCS-ECAT with NJ501-R Series		

^{*1} Payload includes any object(s) attached to a robot link or tool flange, including end-effectors, tooling, valves, grippers, and objects being handled by the robot.

^{*2} Standard and Cleanroom models have a base protection rating of IP40. IP54/65 models have a base protection rating of IP54.

^{*3} Standard and Cleanroom models have a joint protection rating of IP40. IP54/65 models have a joint protection rating of IP65.

^{*4} Cleanroom models only. Standard and IP54/65 models have no Cleanroom rating.

^{*5} Use Sysmac Studio for Integrated Control robots. Use ACE for Standard Control robots. ePLC is only used with Standard Control robots.

^{*6} For Standard Control robots only.

^{*7} eMB-60R and SmartController EX with eV+ 2.3 or above support ePLC functionality with NJ/NX/NY series controllers.

Viper Series

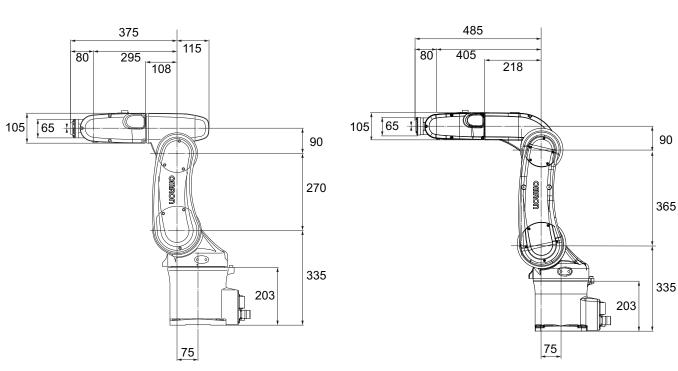
Items Included With the Robot

Item		Description	
Integrated Control Models	eCS-ECAT	Robot Controller and Amplifier	
	eMB-60R	Robot Controller and Amplifier	
Standard Control Models	XSYS Cable	Connects SmartController EX with XSYSTEM connection of eMB-60f (SmartController EX Bundle only)	
	Firewire Cable	4.5 m FireWire cable (SmartController EX Bundle only)	
	SmartController EX	Controls up to four robots (SmartController EX Bundle only)	
	DC Control Power Connector	Control power connector and pins	
	AC High Power Connector	High power connector and pins	
	Robot Power Cable	4 m cable connects eMB-60R to Robot	
	XSYSTEM Cable	1.8 m cable providing 3 connectors for XMCP, XFP, and XUSR signals	
	Front Panel	Remote mounted device for robot mode, power, indication, and emergency stop	
	XMCP Connector Jumper	Jumper for XMCP connector on XSYSTEM cable	
All Models	XFP Connector Jumper	Jumper for XFP connector on XSYSTEM cable	
	XUSR Connector Jumper	Jumper for XUSR connector on XSYSTEM cable	
	Documentation Dongle	USB memory stick containing user manuals (Viper, ACE, and V+) and ACE Software	
	Printed Documentation	Fixed Robot Safety Guide, Declarations of Incorporation (MDOI), and Declaration of Conformance to KC Standards (UKCA)	
	Cable Connectors	Connectors for CN20 and C21 (IP20 bundles only)	
	Cable Connectors and Plugs	Connector and plugs for CN20 and CN21 (IP65 & CR only)	

Options and Additional Items

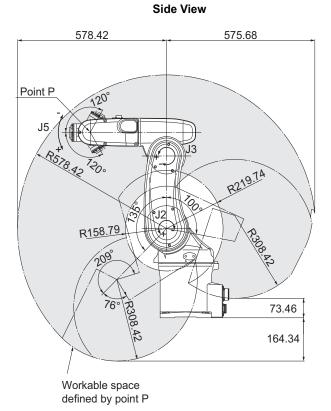
Item	Description	Details	Part Number
IO Blox	Extend the robot's capabilities by providing expandable I/O capacity.	Connects to robot. 0.3 m cables included.	90356-30200
IO Blox (Additional)	Extend the robot's capabilities by providing expandable I/O capacity.	Connects to previous IO Blox. Up to 8 can be added. 0.3 m cables included.	90356-30100
T20 Pendant	Hand held device for moving, teaching and debugging the robot. Includes 10 m cable		10046-010
IPC Application Controller	Allows execution of PackManager and Robot Vision Manager applications.	Includes 24 VDC connector	20152-000
XBELT I/O Adapter Cable	Splits the XBELTIO port on the interface panel into belt encoder, IO Blox, and RS-232 branches.	0.6 m cable length	13463-000
Belt Encoder to M12 Y Adapter Cable	Splits the belt encoder connection on the XBELTIO cable into two belt encoder branches.	3 m cable length	09443-000
EXPIO-to-IOBlox Cable	Connects IO Blox devices to either controller EXPIO connector.	3 m cable length	04677-000
XIO/TIN (Breakout) Cable	Connects to the XIO connector on the controller interface panel to add multiple I/O devices to the system without using an IO Blox unit.	5 m cable length	04465-000
XIO Cable	Connects an XIO Termination Block to the XIO port on the eCS-ECAT interface panel.	2 m cable length	03695-000
200-240 VAC AC Power Cable	Transfers AC power to the robot.	5 m cable	04118-000
Power Supply	Power supply for the robot. Includes 5 m power cable.	24 VDC, 10 A, 240 W	23912-000



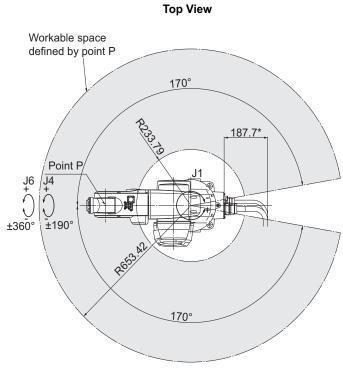


Arm Reach Dimensions

(Unit: mm)

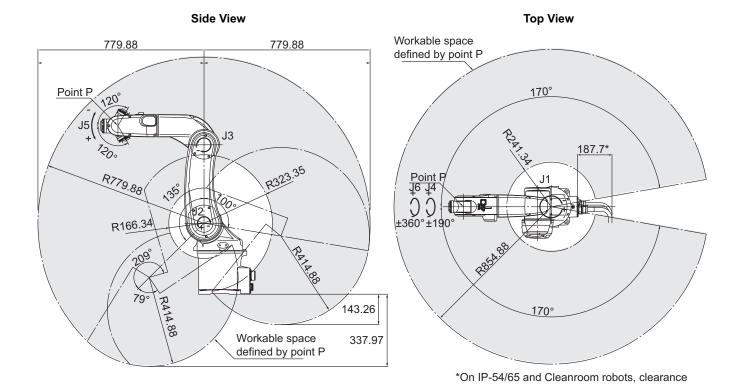


650



*On IP-54/65 and Cleanroom robots, clearance dimension for cables is 222 mm.

850

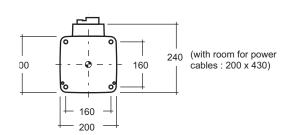


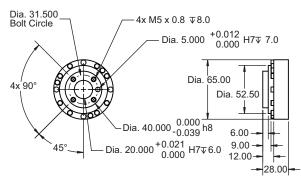
dimension for cables is 222 mm.

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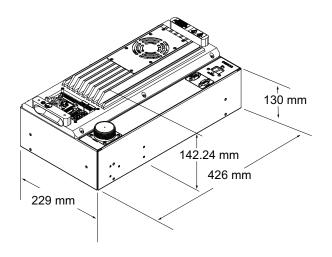
Other Dimensions (Unit: mm)



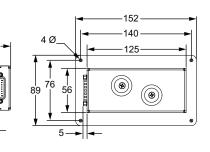




eCS-ECAT / eMB-60R



Front Panel



Related Manuals

Catalog Number	Manual Title
1599	Viper 650/850 Robot with eMB-60R User's Guide
1654	Viper 650/850 Robot with EtherCAT User's Manual
I633	Automation Control Environment (ACE) Version 4 User's Manual
1679	Automation Control Environment (ACE) Version 4 Camera Configuration User's Manual
1609	ACE Sight Reference Guide
1590	Robot Safety Guide
I671	V+ User's Manual
1672	V+ Keyword Reference Manual
I601	T20 Pendant User's Manual
O037	NJ-series Robot Integrated CPU Unit User's Manual
O049	Machine Automation Controller NJ-series Robot Integrated System Startup Guide
W504	Sysmac Studio Version 1 Operation Manual
W595	Sysmac Studio Robot Integrated System Building Function with Robot Integrated CPU Unit Operation Manual
W618	Sysmac Studio 3D Simulation Function Operation Manual
W621	Sysmac Studio Robot Integrated System Building Function with IPC Application Controller Operation Manual

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Viper Series

Note: Do not use this document to operate the Unit.

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